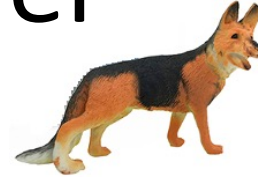


# Dash, Watch Out for Rover



**Challenge:** Drive Dash as close as you can to the dog without hitting him.

**Supplies:** Tape measure and masking tape to mark your starting point.

**Team Name:** The most clever name will be used for tie breaking.

**Code:** Your program can *only* use the following drive function.

```
dash.forward_time(5)
```

Enter number of seconds to drive Dash forward.

**Judging:** When your group is ready, the judge will place the pooch in the road at a random distance from Dash. You may not move the mutt or Dash once the pet is placed. You may *only change the value of time* in the Dash drive statement. Competition distance between bowser and the Dash will be reported in cm. *Don't hit the hound!*

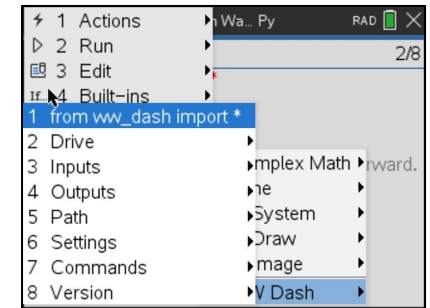
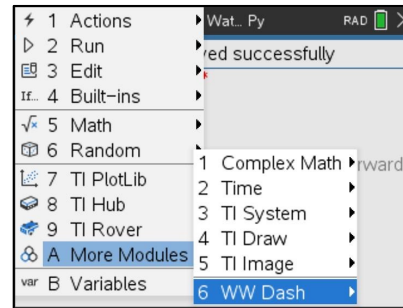
# Watch out for Rover Program

```
1.1 1.2 Dash Wat... Py RAD [status] [close]
```

dashwatch.py saved successfully

```
from ww_dash import *  
  
dash.forward_time(5)  
  
# Change the value of seconds to drive forward.  
# ctrl-r will save your changes and run  
# the program in a Python shell  
# on the next page.
```

from ww\_dash import \*  
is available from the [menu]  
A: More Modules  
then WW Dash menu  
1: from ww\_dash import \*



dash.forward\_time( )  
is available from the WW Dash 2: Drive  
5:Dash Drive with options menu.  
Select item 1:forward\_time( )

